



# **Iterative Learning Control: Robustness and Monotonic Convergence for Interval Systems (Communications and Control Engineering)**

*Hyo-Sung Ahn, Kevin L. Moore, YangQuan Chen*

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This monograph studies the design of robust, monotonically-convergent iterative learning controllers for discrete-time systems. It presents a unified analysis and design framework that enables designers to consider both robustness and monotonic convergence for typical uncertainty models, including parametric interval uncertainties, iteration-domain frequency uncertainty, and iteration-domain stochastic uncertainty. The book shows how to use robust iterative learning control in the face of model uncertainty.

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